

From Newton's Law of Gravitation to Kepler's First Law and Connecting Kepler's 2nd Law to Conservation of Angular Momentum

When a planet P along a curve has polar coordinates (r, θ) , the vectors \mathbf{u}_r and \mathbf{u}_θ are defined by

$$\mathbf{u}_r = \mathbf{i} \cos\theta + \mathbf{j} \sin\theta \text{ and}$$

$$\mathbf{u}_\theta = -\mathbf{i} \sin\theta + \mathbf{j} \cos\theta,$$

where \mathbf{i} and \mathbf{j} are unit vectors in the directions of the positive x - and y -axes. Then \mathbf{u}_r is a unit vector along OP (where O is the focal point of curve) in the direction of increasing r , and \mathbf{u}_θ is a unit vector perpendicular to this in the direction of increasing θ .

Any vector, such as acceleration, \mathbf{a} , can be written in terms of its components in the directions of \mathbf{u}_r and \mathbf{u}_θ . Thus $\mathbf{a} = a_r \mathbf{u}_r + a_\theta \mathbf{u}_\theta$, ...eq (1)

where the component a_r is a scalar and a radial component of acceleration, and the component a_θ is the scalar transverse component.

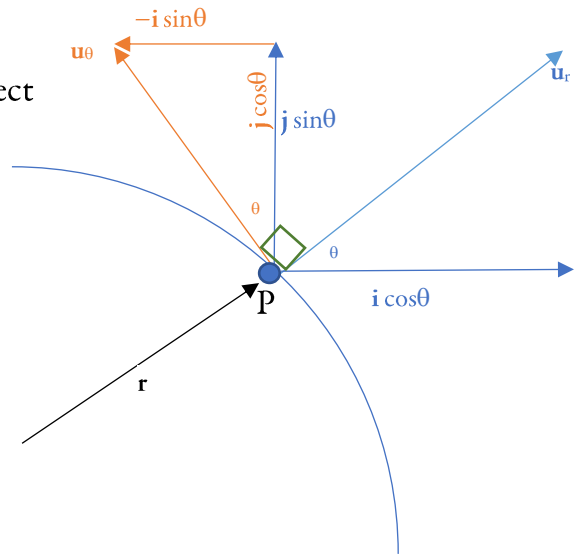
The rate of change of $\mathbf{u}_r = \mathbf{i} \cos\theta + \mathbf{j} \sin\theta$, with respect to time, t , is:

$$\frac{d\mathbf{u}_r}{dt} = \frac{d}{dt} (\mathbf{i} \cos\theta + \mathbf{j} \sin\theta)$$

=

$$\frac{d\mathbf{u}_r}{dt} = \frac{d}{dt} \left(\mathbf{i} \cos\theta \frac{d\theta}{dt} + \mathbf{j} \sin\theta \frac{d\theta}{dt} \right)$$

$$\frac{d\mathbf{u}_r}{dt} = \frac{d}{d\theta} \left(\mathbf{i} \cos\theta \frac{d\theta}{dt} + \mathbf{j} \sin\theta \frac{d\theta}{dt} \right)$$



$$\frac{d\mathbf{u}_r}{dt} = \left(-\mathbf{i} \sin\theta \frac{d\theta}{dt} + \mathbf{j} \cos\theta \frac{d\theta}{dt} \right) = (-\mathbf{i} \sin\theta + \mathbf{j} \cos\theta) \frac{d\theta}{dt} = \mathbf{u}_\theta \frac{d\theta}{dt}$$

Or in shorthand: $\mathbf{u}_r' = \mathbf{u}_\theta \theta'$... (eq 2)

The rate of change of $\mathbf{u}_\theta = -\mathbf{i} \sin\theta + \mathbf{j} \cos\theta$, with respect to time, t , is:

$$\begin{aligned} \frac{(d\mathbf{u}_\theta)}{dt} &= \frac{d}{dt}(-\mathbf{i} \sin\theta + \mathbf{j} \cos\theta) = \frac{d}{dt}\left(-\mathbf{i} \sin\theta \frac{d\theta}{dt} + \mathbf{j} \cos\theta \frac{d\theta}{dt}\right) \\ &= \frac{d}{d\theta}\left(-\mathbf{i} \sin\theta \frac{d\theta}{dt} + \mathbf{j} \cos\theta \frac{d\theta}{dt}\right) = (-\mathbf{i} \cos\theta - \mathbf{j} \sin\theta) \frac{d\theta}{dt} = -\mathbf{u}_r \frac{d\theta}{dt} \end{aligned}$$

Or in shorthand: $\mathbf{u}_\theta' = -\mathbf{u}_r \theta'$... (eq 3)

The velocity of the planet, \mathbf{v} , is the rate of change of the radial vector, \mathbf{r} , with respect to time. The radial vector, \mathbf{r} , in turn equals $r\mathbf{u}_r$.

$$\text{So } \mathbf{v} = \frac{dr}{dt} = \frac{d}{dt}(r\mathbf{u}_r) = r'\mathbf{u}_r + r\mathbf{u}_r'$$

Substituting eq (2) into eq (4):

$$\mathbf{v} = \frac{dr}{dt} = r'\mathbf{u}_r + r\mathbf{u}_\theta \theta'$$

Acceleration is the derivative of velocity with respect to time:

$$\mathbf{a} = \frac{d^2\mathbf{r}}{dt^2} = r''\mathbf{u}_r + r'\mathbf{u}_r' + r'\mathbf{u}_\theta \theta' + r(\mathbf{u}_\theta \theta')'$$

$$r''\mathbf{u}_r + r'\mathbf{u}_r' + r'\mathbf{u}_\theta \theta' + r(\mathbf{u}_\theta' \theta' + \mathbf{u}_\theta \theta'')$$
 Substituting equations (2) and (3)

$$= r''\mathbf{u}_r + r'\mathbf{u}_\theta \theta' + r'\mathbf{u}_\theta \theta' + r(-\mathbf{u}_r \theta' \theta' + \mathbf{u}_\theta \theta'')$$

$$\mathbf{a} = \mathbf{u}_r(r'' - r(\theta')^2) + \mathbf{u}_\theta(2r'\theta' + r\theta'')$$
 ... eq (4)

Recall equation (1): $\mathbf{a} = a_r\mathbf{u}_r + a_\theta\mathbf{u}_\theta$,

So $a_r = r'' - r(\theta')^2$ and $a_\theta = 2r'\theta' + r\theta''$...eq (5a) and (5b)

Conservation of Angular Momentum

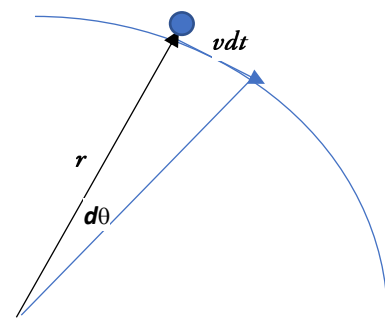
The area of the triangular region is $\frac{1}{2}$ the cross product of

$$r \text{ and } vdt \text{ or } dA = \frac{r \times vdt}{2}$$

$$\frac{dA}{dt} = \frac{r \times v}{2}$$
 Multiply both sides by the mass of the planet,

$$m \frac{dA}{dt} = \frac{r \times m v}{2} = \frac{L}{2}$$
 where L is the angular momentum.

$$\frac{dA}{dt} = \frac{L}{2m}$$



...eq(6)

From Kepler's 2nd Law which observed that planets sweep equal areas in equal times, we know that $\frac{L}{2m}$ is a constant. In addition, if the force between a planet and its star is a central force, F , then the torque, t , which is the cross product between r and F will equal zero.

Since F is the change in momentum, p with respect to time,

$$t = r \times F = 0 = r \times \frac{dp}{dt} = r \times \frac{mv}{dt} = \frac{dL}{dt} = 0$$

If the rate of change of momentum is zero then L must be a constant, and L is conserved.

In eq(6), let the constant $h = L/m$.

$$\frac{dA}{dt} = \frac{h}{2} \quad \dots\text{eq (7)}$$

For polar equations, where r is a function of θ ,

$$dA = \frac{r^2 d\theta}{2} \quad \text{Dividing both sides by } dt \text{ and then comparing to eq (7)}$$

$$\frac{dA}{dt} = \frac{r^2 d\theta}{2 dt} = \frac{h}{2} \cdot \text{Solving for } \frac{d\theta}{dt} = \frac{h}{r^2} \quad \dots\text{eq (8)}$$

Since $r^2 \frac{d\theta}{dt} = h = \text{constant}$, if we differentiate implicitly,

$$(r^2 \theta')' = h' = 0$$

$$2rr' \theta' + r^2 \theta'' = 0 \dots \text{dividing through by } r:$$

$$2r' \theta' + r \theta'' = 0. \quad \dots\text{eq (9)}$$

Returning to eq (5a) and (5b):

$$a_r = r'' - r(\theta')^2 \text{ and } a_\theta = 2r'\theta' + r\theta'' \quad \text{eq (5a) and (5b)}$$

By comparing eq 5(b) to eq 9, we notice that $a_\theta = 0$, and since $\mathbf{a} = a_r \mathbf{u}_r + a_\theta \mathbf{u}_\theta$, eq(1),

$$\mathbf{a} = a_r \mathbf{u}_r = (r'' - r(\theta')^2) \mathbf{u}_r$$

According to Newton's gravitational law, the central force is inversely proportional to the square of the radius and directly proportional to the product of the mass of the planet, m , and the mass of the sun, M . It acts towards the center and is therefore in the direction opposite to the radial vector u_r .

$$F = -\frac{GMm}{r^2}u_r. \text{ By the law of inertia } F = ma = ma_r u_r$$

Equating the above two we get:

$$-\frac{GMm}{r^2}u_r = ma_r u_r$$

$$\text{Or } -\frac{GM}{r^2} = a_r \quad \dots \text{eq (10)}$$

Substituting eq (5a) $a_r = r'' - r(\theta')^2$ into eq 10:

$$r'' - r(\theta')^2 = -\frac{GM}{r^2} \quad \dots \text{eq(11)}$$

To solve the above differential equation, we choose a function $w(\theta)$, such that $w = 1/r$ or $r = 1/w$... eq(12)

$$w' = \frac{dw}{d\theta} = \frac{d}{d\theta} \left(\frac{1}{r} \right) = \frac{d}{d\theta} \left(\frac{1}{r} \right) \frac{dr}{dr} = \frac{d}{dr} \left(\frac{1}{r} \right) \frac{dr}{d\theta} = \left(\frac{-1}{r^2} \right) \frac{dr}{d\theta}$$

$$w' = \left(\frac{-1}{r^2} \right) \frac{dr}{d\theta} \text{ and solving for } \frac{dr}{d\theta},$$

$$\frac{dr}{d\theta} = -r^2 w' \frac{d\theta}{dt}, \text{ but from eq (8), } \frac{d\theta}{dt} = \frac{h}{r^2}$$

$$\frac{dr}{dt} = -r^2 w' \frac{h}{r^2} = -hw'$$

$$\frac{d^2r}{dt^2} = -h \frac{d}{dt} \left(\frac{dw}{d\theta} \right) = -h \frac{d}{d\theta} \left(\frac{dw}{dt} \right) = -h \frac{d}{d\theta} \left(\frac{dw}{d\theta} \right) \left(\frac{d\theta}{dt} \right)$$

$$\frac{d^2r}{dt^2} = r'' = -h \frac{d^2w}{d\theta^2} \left(\frac{d\theta}{dt} \right) = -hw'' \frac{h}{r^2} = -h^2 w'' w^2 \quad \dots \text{eq(13)}$$

Substitute eqs (8), (12) and (13) into eq (11):

$$-h^2 w'' w^2 - \frac{1}{w} \left(\frac{h}{r^2} \right)^2 = -w^2 GM \text{ or}$$

$$-h^2 w'' w^2 - \frac{1}{w} (h^2 w^4) = -w^2 GM \quad \text{Dividing through by } -h^2 w^2,$$

$$w'' + w = \frac{GM}{h^2}$$

$$w(D^2 + 1) = \frac{GM}{h^2}$$

A particular solution to the above differential equation is $w = A \cos\theta + \frac{GM}{h^2}$

But $w = 1/r = A \cos\theta + \frac{GM}{h^2}$

$$r = \frac{1}{\frac{GM}{h^2} + A \cos\theta} = \frac{1}{\frac{GM}{h^2} + A \cos\theta} \left[\frac{h^2}{GM} \right] = \frac{\frac{h^2}{GM}}{1 + A \frac{h^2}{GM} \cos\theta}, \text{ which is in the form}$$

$$r = \frac{pe}{1 + e \cos\theta}, \text{ which is an ellipse.} \quad \dots \text{Eq(14)}$$